

RS485-MODBUS-ETHERNET MODBUS ROUTER WITH ETHERNET AND CAN

USER MANUAL

P/N: AX141810A, AX141830A

VERSION HISTORY

| Version | Date | Author | Modification |
|---------|-------------------|---------------|---|
| 1.0.0. | May 9, 2023 | Antti Keränen | Initial Draft |
| 1.0.1 | May 16, 2023 | M Ejaz | Added Technical Specifications Fixed legacy issues |
| 1.0.2 | February 6, 2024 | M Ejaz | Updated technical specifications |
| 1.0.3 | February 13, 2024 | M Ejaz | Updated temperature ratings |
| 1.0.4 | February 15, 2024 | M Ejaz | Added a note about default Ethernet settings where default passwords are mentioned. |



The default passwords:

AX141810A firmware: **'AX141810A'**

AX141830A firmware: **'AX141830A'**

For default Ethernet settings, please go to section 5.2.

ACCRONYMS

| | |
|----------|--|
| ACK | Positive Acknowledgement (from SAE J1939 standard) |
| BATT +/- | Battery positive (a.k.a. Vps) or Battery Negative (a.k.a. GND) |
| DM | Diagnostic Message (from SAE J1939 standard) |
| DTC | Diagnostic Trouble Code (from SAE J1939 standard) |
| EA | Axiomatic Electronic Assistant (A Service Tool for Axiomatic ECUs) |
| ECU | Electronic Control Unit (from SAE J1939 standard) |
| GND | Ground reference (a.k.a. BATT-) |
| I/O | Inputs and Outputs |
| IP | Internet Protocol |
| MAC | Media Access Control |
| MAP | Memory Access Protocol |
| MB | Modbus |
| NAK | Negative Acknowledgement (from SAE J1939 standard) |
| PDU1 | A format for messages that are to be sent to a destination address, either specific or global (from SAE J1939 standard) |
| PDU2 | A format used to send information that has been labeled using the Group Extension technique, and does not contain a destination address. |
| PGN | Parameter Group Number (from SAE J1939 standard) |
| PropA | Message that uses the Proprietary A PGN for peer-to-peer communication |
| PropB | Message that uses a Proprietary B PGN for broadcast communication |
| SPN | Suspect Parameter Number (from SAE J1939 standard) |
| TCP/IP | Transmission Control Protocol / Internet Protocol |
| TP | Transport Protocol |
| Vps | Voltage Power Supply (a.k.a. BATT+) |

TABLE OF CONTENTS

- 1. OVERVIEW OF CONTROLLER 7**
- 2. INSTALLATION INSTRUCTIONS 8**
 - 2.1. Dimensions and Pinout..... 8
- 3. OVERVIEW OF J1939 FEATURES..... 10**
 - 3.1. Introduction to Supported Messages..... 10
 - 3.2. NAME, Address and Identification Information..... 11
- 4. WEB BROWSER BASED CONTROLLER CONFIGURATION 14**
- 5. ECU SETPOINTS ACCESSED WITH AXIOMATIC ELECTRONIC ASSISTANT 23**
 - 5.1. J1939 Network Setpoints..... 23
 - 5.2. Ethernet Parameter Setpoints 24
 - 5.3. RS485 Parameter Setpoints 25
- 6. REFLASHING OVER ETHERNET USING A WEB BROWSER 26**
- APPENDIX A - TECHNICAL SPECIFICATION.....A-1**

List of Figures

| | |
|---|----|
| Figure 1 – Block diagram of the RS485-MODBUS Converter with Ethernet and CAN..... | 7 |
| Figure 2 – Controller Dimensions and Label | 8 |
| Figure 3 – Screen Capture of J1939 Setpoints | 23 |
| Figure 4 – Screen Capture of Ethernet Parameter Setpoints | 24 |
| Figure 5 – Screen Capture of RS485 Parameter Setpoints | 25 |

List of Tables

| | |
|--|----|
| Table 1 – AX141810A/AX141830A Connector Pinout | 9 |
| Table 2 – J1939 Setpoints..... | 23 |
| Table 3 – Ethernet Parameter Setpoints | 24 |
| Table 4 – RS485 Parameter Setpoints..... | 25 |

REFERENCES

| | |
|-------------|---|
| J1939 | Recommended Practice for a Serial Control and Communications Vehicle Network, SAE, April 2011 |
| J1939/21 | Data Link Layer, SAE, December 2010 |
| J1939/71 | Vehicle Application Layer, SAE, March 2011 |
| J1939/73 | Application Layer-Diagnostics, SAE, February 2010 |
| J1939/81 | Network Management, SAE, March 2017 |
| TDAX141810A | Technical Datasheet, RS485-MODBUS-ENET Converter, Axiomatic Technologies 2023 |
| UMAX07050x | User Manual, Axiomatic Electronic Assistant and USB-CAN, Axiomatic Technologies, May 2023 |

This document assumes the reader is familiar with the SAE J1939 standard. Terminology from the standard is used, but not described in this document.



NOTE: This product is supported by Axiomatic Electronic Assistant V5.15.129.0 and higher

1. OVERVIEW OF CONTROLLER

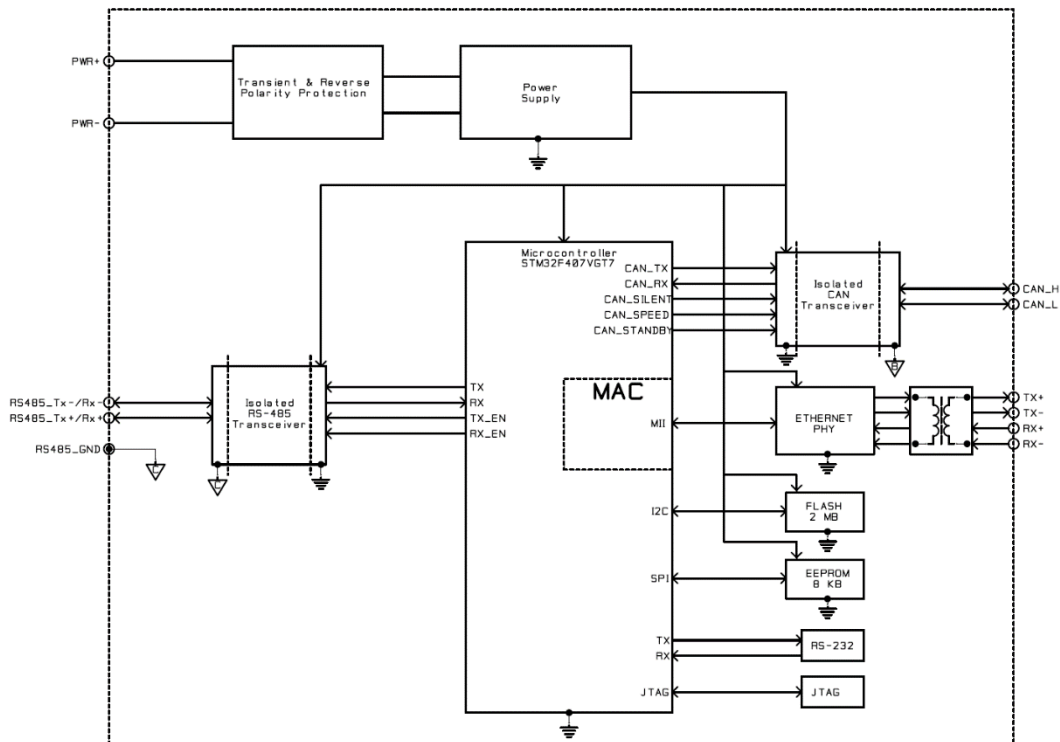


Figure 1 – Block diagram of the RS485-MODBUS Converter with Ethernet and CAN

The RS485-MODBUS Converter with Ethernet and CAN (later RS485-MODBUS-ENET) is a device that forwards Modbus data between the serial port (RTU), CAN and Ethernet based on a custom routing configuration. The configuration can be done using a web browser and the built-in web server running on the RS485-MODBUS-ENET device.

The Axiomatic Electronic Assistant can be used to configure the network parameters (both RS485 and Ethernet) of the RS485-MODBUS-ENET device. The web browser interface (TCP port 80) supports the configuration of all parameters, also including the ones that have EA configuration support.

The two firmware versions, AX141810A and AX141830A both support the same data routing functions. The difference is in the amount of routing rules and message definitions. The AX141810A is a general-purpose device with support for both directions, Modbus (RTU+TCP/IP) to CAN and vice versa.

The AX141830A is targeted mainly for CAN to Modbus (RTU+TCP/IP) direction.

2. INSTALLATION INSTRUCTIONS

2.1. Dimensions and Pinout

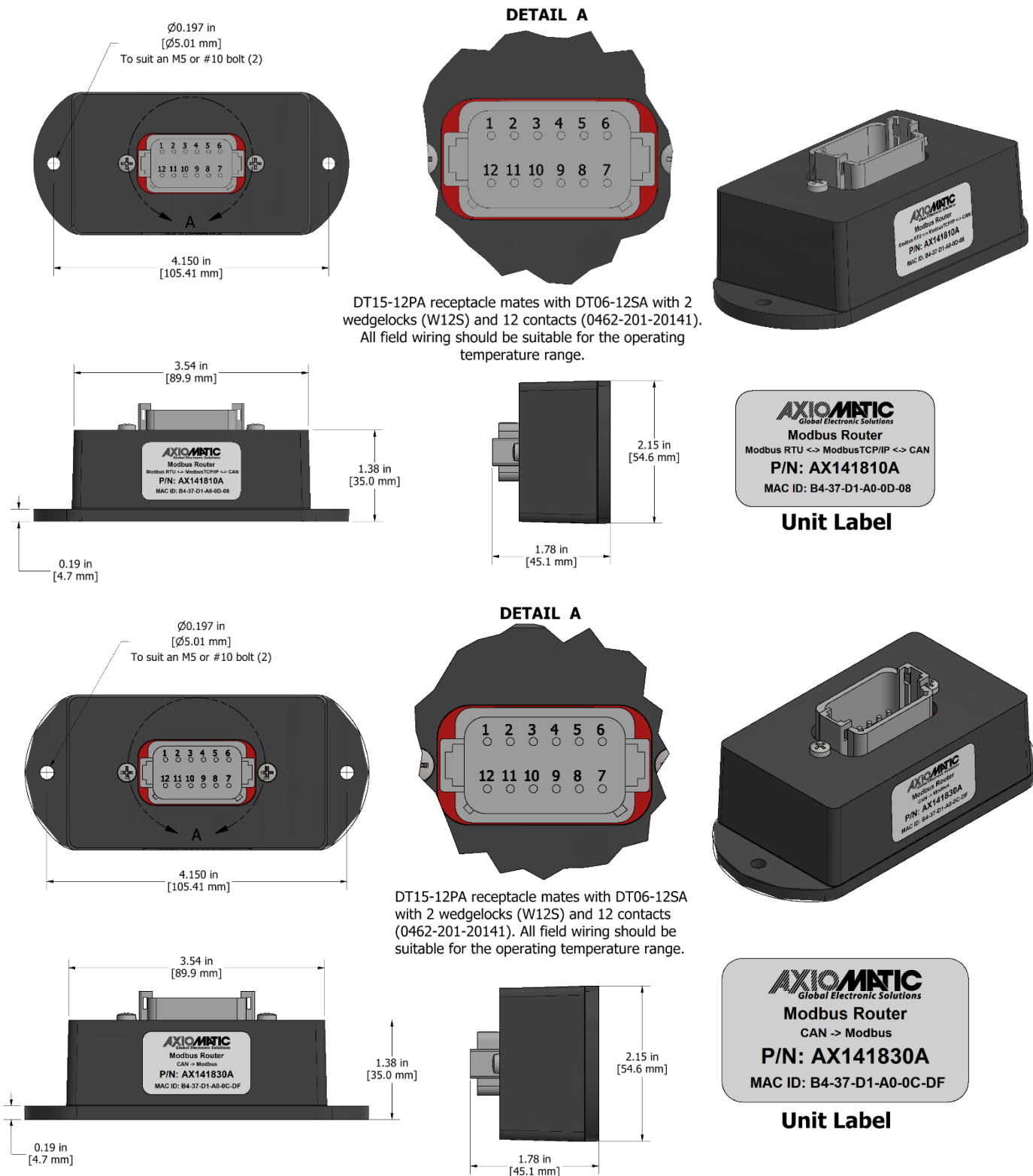


Figure 2 – Controller Dimensions and Label

| CAN and I/O Connector | |
|------------------------------|--------------------|
| Pin # | Description |
| 1 | BATT- |
| 2 | Ethernet TX+ |
| 3 | Ethernet RX+ |
| 4 | RS485_TX+/RX+ |
| 5 | CAN_SH |
| 6 | CAN_H |
| 7 | CAN_L |
| 8 | RS485_GND |
| 9 | RS485_TX-/RX- |
| 10 | Ethernet RX- |
| 11 | Ethernet TX- |
| 12 | BATT+ |

Table 1 – AX141810A/AX141830A Connector Pinout

3. OVERVIEW OF J1939 FEATURES

The software was designed to provide flexibility to the user with respect to messages sent from the ECU by providing:

- Configurable ECU Instance in the NAME (to allow multiple ECUs on the same network)
- Configurable PGN and Data Parameters
- Configurable Diagnostic Messaging Parameters, as required

3.1. Introduction to Supported Messages

The ECU is compliant with the standard SAE J1939, and supports following PGNs from the standard.

From J1939-21 – Data Link Layer

- Request 59904 0x00EA00
- Acknowledgement 59392 0x00E800
- Transport Protocol – Connection Management 60416 0x00EC00
- Transport Protocol – Data Transfer Message 60160 0x00EB00
- Proprietary B from 65280 0x00FF00
to 65535 0x00FFFF

From J1939-73 – Diagnostics

- DM1 – Active Diagnostic Trouble Codes 65226 0x00FECA
- DM2 – Previously Active Diagnostic Trouble Codes 65227 0x00FECB
- DM3 – Diagnostic Data Clear/Reset for Previously Active DTCs 65228 0x00FECC
- DM11 – Diagnostic Data Clear/Reset for Active DTCs 65235 0x00FED3

From J1939-81 – Network Management

- Address Claimed/Cannot Claim 60928 0x00EE00
- Commanded Address 65240 0x00FED8

From J1939-71 – Vehicle Application Layer

- ECU Identification Information 64965 0x00FDC5
- Software Identification 65242 0x00FEDA
- Component Identification 65259 0x00FEEB

None of the application layer PGNs are supported as part of the default configurations, but they can be selected as desired for transmit function blocks.

Setpoints are accessed using standard Memory Access Protocol (MAP) with proprietary addresses. The Axiomatic Electronic Assistant (EA) allows for quick and easy configuration of some of the unit's main parameters over CAN network.

3.2. NAME, Address and Identification Information

The RS485-MODBUS-ENET has the following default for the J1939 NAME. The user should refer to the SAE J1939/81 standard for more information on these parameters and their ranges.

| | |
|---------------------------|---|
| Arbitrary Address Capable | Yes |
| Industry Group | 0, Global |
| Vehicle System Instance | 0 |
| Vehicle System | 0, Non-specific system |
| Function | 25, Axiomatic Protocol Converter |
| Function Instance | 23/24, Axiomatic AX141810A/AX141830A |
| ECU Instance | 0, First Instance |
| Manufacture Code | 162, Axiomatic Technologies |
| Identity Number | Variable, uniquely assigned during factory programming for each ECU |

The ECU Instance is a configurable setpoint associated with the NAME. Changing this value will allow multiple ECUs of this type to be distinguishable from one another when they are connected on the same network.

The default value of the “ECU Address” setpoint is 128 (0x80), which is the preferred starting address for self-configurable ECUs as set by the SAE in J1939 tables B3 and B7. The EA will allow the selection of any address between 0 and 253. ***It is the user’s responsibility to select an address that complies with the standard.*** The user must also be aware that since the unit is arbitrary address capable, if another ECU with a higher priority NAME contends for the selected address, the RS485-MODBUS-ENET will continue select the next highest address until it finds one that it can claim. See J1939/81 for more details about address claiming.

ECU Identification Information

| | | | |
|-------------------------------|---------------------------------|---|--------|
| PGN 64965 | ECU Identification Information | | -ECUID |
| Transmission Repetition Rate: | On request | | |
| Data Length: | Variable | | |
| Extended Data Page: | 0 | | |
| Data Page: | 0 | | |
| PDU Format: | 253 | | |
| PDU Specific: | 197 PGN Supporting Information: | | |
| Default Priority: | 6 | | |
| Parameter Group Number: | 64965 (0x00FDC5) | | |
| Start Position | Length | Parameter Name | SPN |
| a | Variable | ECU Part Number, Delimiter (ASCII "**") | 2901 |
| b | Variable | ECU Serial Number, Delimiter (ASCII "**") | 2902 |
| c | Variable | ECU Location, Delimiter (ASCII "**") | 2903 |
| d | Variable | ECU Type, Delimiter (ASCII "**") | 2904 |
| e | Variable | ECU Manufacturer Name, Delimiter (ASCII "**") | 4304 |
| (a)*(b)*(c)*(d)*(e)* | | | |

Software Identifier

| | | | |
|-------------------------------|---------------------------------|--|-------|
| PGN 65242 | Software Identification | | -SOFT |
| Transmission Repetition Rate: | On request | | |
| Data Length: | Variable | | |
| Extended Data Page: | 0 | | |
| Data Page: | 0 | | |
| PDU Format: | 254 | | |
| PDU Specific: | 218 PGN Supporting Information: | | |
| Default Priority: | 6 | | |
| Parameter Group Number: | 65242 (0x00FEDA) | | |
| Start Position | Length | Parameter Name | SPN |
| 1 | 1 Byte | Number of software identification fields | 965 |
| 2-n | Variable | Software identification(s), Delimiter (ASCII "**") | 234 |

Byte 1 is set to 5, and the identification fields are as follows.

(Part Number)*(Version)*(Date)*(Owner)*(Description)

The EA shows all this information in its "General ECU Information" page. *Note: The information provided in the Software ID is available for any J1939 service tool which supports the PGN -SOFT*

Component Identification

| | | | |
|-------------------------------|----------|---|-----|
| PGN 65259 | | Component Identification | -CI |
| Transmission Repetition Rate: | | On request | |
| Data Length: | | Variable | |
| Extended Data Page: | | 0 | |
| Data Page: | | 0 | |
| PDU Format: | | 254 | |
| PDU Specific: | | 235 PGN Supporting Information: | |
| Default Priority: | | 6 | |
| Parameter Group Number: | | 65259 (0x00FEEB) | |
| Start Position | Length | Parameter Name | SPN |
| a | 1-5 Byte | Make, Delimiter (ASCII “*”) | 586 |
| b | Variable | Model, Delimiter (ASCII “*”) | 587 |
| c | Variable | Serial Number, Delimiter (ASCII “*”) | 588 |
| d | Variable | Unit Number (Power Unit), Delimiter (ASCII “*”) | 233 |
| (a)*(b)*(c)*(d)*(e)* | | | |

4. WEB BROWSER BASED CONTROLLER CONFIGURATION

The RS485-MODBUS-ENET controller supports configuration of the data routing parameters from Ethernet port using a standard web browser.

The web browser-based configuration requires a password before any of the parameters can be viewed or edited.



The default passwords:

AX141810 firmware: '**AX141810A**'

AX141830 firmware: '**AX141830A**'

For default Ethernet settings, please go to section 5.2.

4.1. Parameter Editing

The RS485-MODBUS-ENET has a web server running on TCP port 80. Please note that the “Save settings” button must be pressed to save the parameters. If not, the modified parameters are discarded when moving to another configuration page or closing the web browser. The RS485-MODBUS-ENET web server supports the configuration options described on the following pages.

<configured ip>

<configured ip>/index.shtml

The screenshot displays the web interface for the AX141810 ModbusRTU - ModbusTCP/IP Converter. The browser address bar shows the URL `192.168.1.20/index.shtml`. The page features a navigation menu on the left with links to Home, Main Settings, CAN RX Settings, CAN TX Settings, Modbus Slave Settings, Modbus Master Settings, Diagnostics Routing, Settings, Upload/Download, and Firmware. The main content area is divided into several sections:

- DEVICE INFORMATION:** Part Number: AX141810A, Serial Number: 0007823001, Firmware Version: V97.99, Latest Settings File: AX141810_settings(1).bin
- ETHERNET:** MAC Address: B4:37:D1:A5:78:99. The Server section shows Device IP Address: 192.168.1.20, Web Server Port: 80, Device Subnet Mask: 255.255.255.0, and Gateway IP Address: 192.168.1.1. The Client section shows Remote IP Address: 192.168.1.49 and Remote Port: 502.
- CAN:** Baud Rate: 250 kbit/s, Auto Baud Rate Enabled: Yes
- RS485:** RS485 settings: 9600, 8N1
- DIAGNOSTICS:** CAN Frames Received: 40, CAN Frames Sent: 73, RS485 Frames Received: 0, RS485 Frames Sent: 0, RS485 Errors Detected: 0, Ethernet Messages Received: 809, Ethernet Messages Sent: 467, Modbus Messages Sent: 13, Modbus Replies Received: 0, Modbus Exceptions Received: 0, Modbus CRC Errors: 0, CPU Temperature (Deg C): 37.77

The Home page (index.shtml) shows the main configuration parameters and communication statistics for the different interfaces.

<configured ip>/main_settings.shtml

The Main Settings configuration page allows the user to modify the device's IP address, netmask and the main configuration parameters for the communication interfaces. The CAN configuration parameters include the default baud rate to use and the auto-baud rate capability.

The serial port configuration contains baud rate (freely settable in range 75bps...256kbps), number of data bits, start and stop bits and parity.

The password can be changed by entering the same password to both **New password** and **Retype new password** entries. In case the **Retype new password** is left empty or the two passwords don't match, the password is not modified.

AX141810 Main Settings

192.168.1.20/main_settings.shtml

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ModbusRTU -
ModbusTCP/IP Converter

- [Home](#)
- [Main Settings](#)
- [CAN RX Settings](#)
- [CAN TX Settings](#)
- [Modbus Slave Settings](#)
- [Modbus Master Settings](#)
- [Diagnostics Routing](#)
- [Settings](#)
- [Upload/Download](#)
- [Firmware](#)

MAIN SETTINGS

Save Settings Discard Changes Set Defaults

ETHERNET

Server (Modbus Slave & Web Configuration)

Device IP Address: 192.168.1.20

Web Server Port: 80

Device Subnet Mask: 255.255.255.0

Gateway IP Address: 192.168.1.1

Client (Modbus Master)

Remote IP Address: 192.168.1.49

Remote Port: 502

CAN

Baud Rate: 250 kbit/s

Auto baudrate enabled: Yes

RS485

Baud rate: 9600

Number of data bits: 8

Parity: None

Number of stop bits: 1

Password

New password:

Retype new password:

Reboot

Reboot controller Enable rebooting

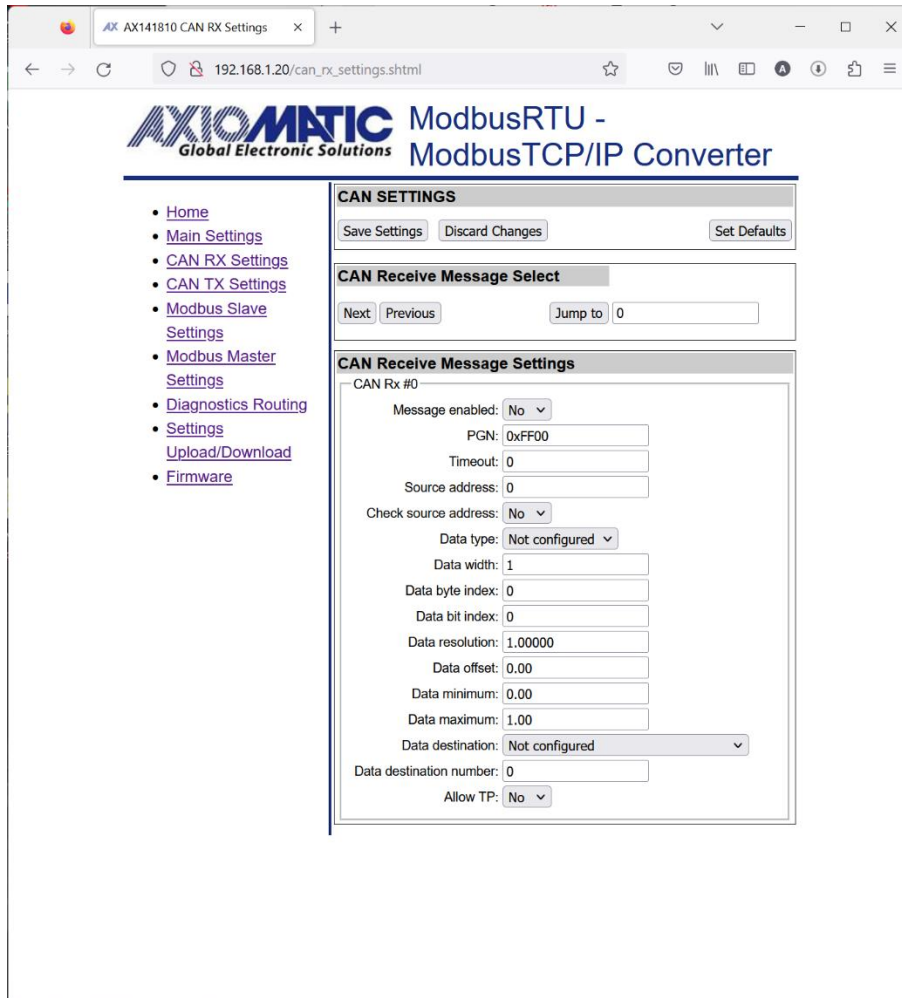
<configured ip>/can_rx_settings.shtml

The CAN receive message parameter settings are displayed one message at a time. The message can be selected using the 'Next' and 'Previous' buttons. The 'Jump to' button selects the specified message directly. Please remember to save settings before selecting another CAN receive message to be configured, otherwise the modified settings will be lost.

The 'Discrete' data type reads in the CAN data as a number (or bit field data), using the range specified by the configured number of bits (**Data width**). With discrete data types, the resolution, offset, minimum and maximum are not used.

The 'Continuous' data type uses the J1939 data formatting with resolution, offset, minimum and maximum values. With continuous data, the data range is limited for reserving the upper range for J1939 special and error codes.

The Data destination and Data destination number settings specify the target interface for the received data. The received data is always stored to a local variable assigned for each CAN receive message, but the Data destination needs to be configured for forwarding the data to the Modbus slave interfaces.



AX141810 CAN RX Settings

192.168.1.20/can_rx_settings.shtml

AXIOMATIC Global Electronic Solutions
ModbusRTU - ModbusTCP/IP Converter

- [Home](#)
- [Main Settings](#)
- [CAN RX Settings](#)
- [CAN TX Settings](#)
- [Modbus Slave Settings](#)
- [Modbus Master Settings](#)
- [Diagnostics Routing Settings](#)
- [Settings](#)
- [Upload/Download](#)
- [Firmware](#)

CAN SETTINGS

Save Settings Discard Changes Set Defaults

CAN Receive Message Select

Next Previous Jump to 0

CAN Receive Message Settings

CAN Rx #0

Message enabled: No

PGN: 0xFF00

Timeout: 0

Source address: 0

Check source address: No

Data type: Not configured

Data width: 1

Data byte index: 0

Data bit index: 0

Data resolution: 1.00000

Data offset: 0.00

Data minimum: 0.00

Data maximum: 1.00

Data destination: Not configured

Data destination number: 0

Allow TP: No

<configured ip>/can_tx_settings.shtml

Each of the CAN transmit messages support several signals for sending out received data. The transmit messages support the same 'Discrete' and 'Continuous' data types with same characteristics than the CAN receive messages do.

Please remember to save the settings before selecting a new transmit message or transmit signal. In case the values are not saved, the modifications are lost when a new message or signal is selected.

The screenshot displays the web interface for the AXIOMATIC ModbusRTU - ModbusTCP/IP Converter. The browser address bar shows the URL `192.168.1.20/can_tx_settings.shtml`. The page features a navigation menu on the left with links to Home, Main Settings, CAN RX Settings, CAN TX Settings, Modbus Slave Settings, Modbus Master Settings, Diagnostics Routing, Settings, Upload/Download, and Firmware. The main content area is titled "CAN SETTINGS" and includes a "Save Settings" button, a "Discard Changes" button, and a "Set Defaults" button. Below this, there are sections for "CAN Transmit Message Select" and "CAN Transmit Signal Select", each with "Next", "Previous", and "Jump to" controls. The "CAN Transmit Message Settings" section is currently active, showing fields for "CAN Tx #0", "Message enabled" (set to "No"), "PGN" (0xFF80), "TX interval" (0), "Priority" (6), and "Destination address" (0). The "CAN Transmit Signal Settings" section is also visible, showing fields for "CAN Tx #0 Signal #0", "Signal data source" (Not configured), "Signal data number" (0), "Signal data type" (Not configured), "Signal data width" (1), "Signal data byte index" (0), "Signal data bit index" (0), "Signal data resolution" (1.00000), "Signal data offset" (0.00), "Signal data minimum" (0.00), and "Signal data maximum" (1.00).

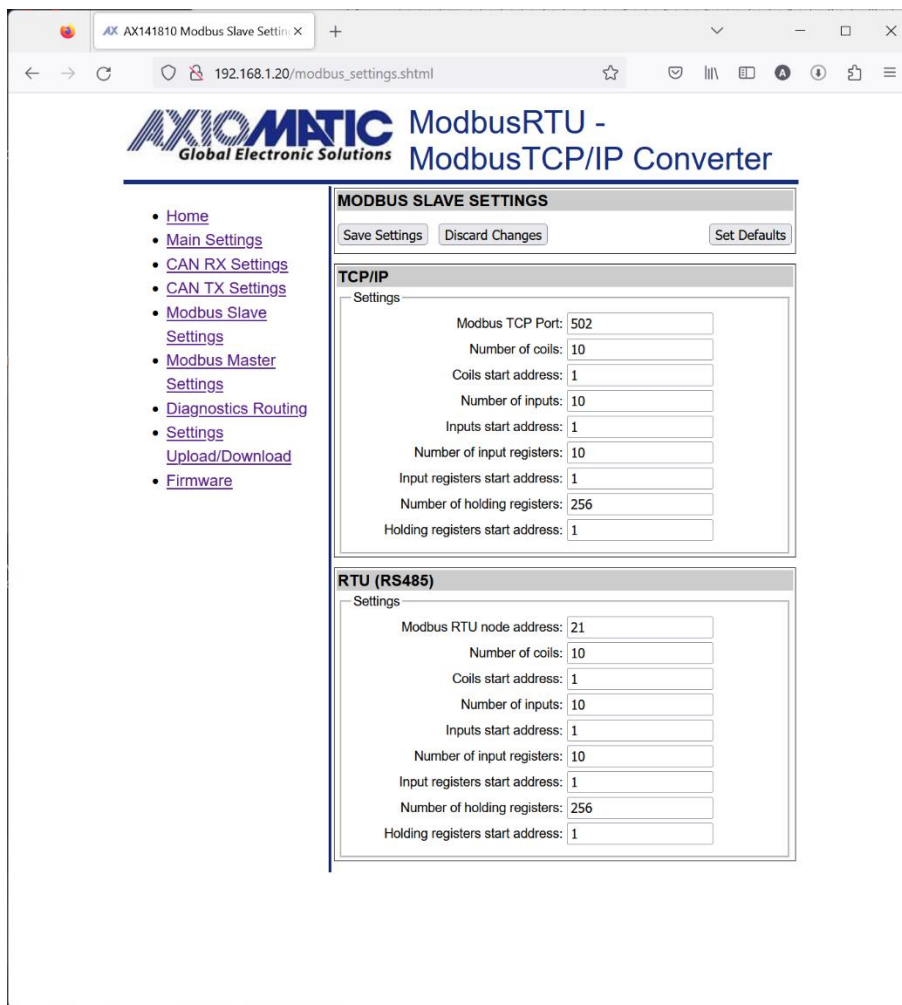
<configured ip>/modbus_settings.shtml

The RS485-MODBUS-ENET device supports Modbus RTU and Modbus TCP/IP slaves running on the RS485 and Ethernet ports, respectively. The number and start address for each of the Modbus slave's inputs, coils and registers can be specified.

Please note that the slave interface is enabled only if the Modbus master implementation is not running on that interface.

The Modbus TCP/IP node address is a "don't care", but the RTU slave interface will read in only the messages that are targeted to the configured Modbus node address.

The number of inputs, coils and registers have an upper limit, and the web server will not accept values beyond the built-in maximum limit. If the upper limit is exceeded, the value is saturated to the maximum allowed value.



AXIOMATIC Global Electronic Solutions ModbusRTU - ModbusTCP/IP Converter

- [Home](#)
- [Main Settings](#)
- [CAN RX Settings](#)
- [CAN TX Settings](#)
- [Modbus Slave Settings](#)
- [Modbus Master Settings](#)
- [Diagnostics Routing](#)
- [Settings](#)
- [Upload/Download](#)
- [Firmware](#)

MODBUS SLAVE SETTINGS

Save Settings Discard Changes Set Defaults

TCP/IP Settings

Modbus TCP Port: 502
Number of coils: 10
Coils start address: 1
Number of inputs: 10
Inputs start address: 1
Number of input registers: 10
Input registers start address: 1
Number of holding registers: 256
Holding registers start address: 1

RTU (RS485) Settings

Modbus RTU node address: 21
Number of coils: 10
Coils start address: 1
Number of inputs: 10
Inputs start address: 1
Number of input registers: 10
Input registers start address: 1
Number of holding registers: 256
Holding registers start address: 1

<configured ip>/modbus_master.shtml

The RS485-MODBUS-ENET device supports Modbus RTU and Modbus TCP/IP master running on the RS485 and Ethernet ports, respectively. The “Ethernet master enabled” and “RS485 master enabled” options need to be set to ‘Yes’ for enabling the corresponding Modbus master.

Please note that enabling the Modbus master will disable the corresponding Modbus slave.

The **Forward received data to** and **Default source for writes** data routing options are the built-in variables for each Modbus master message definition. The CAN receive messages’ **Data destination** configuration can access these variables directly if configured to do so on the CAN receive message configuration page.

The received Modbus data can be also sent directly to CAN bus by selecting the ‘Direct CAN TX’ option for the **Forward received data to** setpoint. In this case, the **Received data number** specifies the J1939 PGN to use (the priority will default to 6 and the RS485-MODBUS-ENET’s J1939 address will be used as the source address for the direct transmit messages).

The screenshot displays the web interface for the AXIOMATIC ModbusRTU - ModbusTCP/IP Converter. The browser address bar shows the URL 192.168.1.20/modbus_master.shtml. The page features a navigation menu on the left with links for Home, Main Settings, CAN RX Settings, CAN TX Settings, Modbus Slave Settings, Modbus Master Settings, Diagnostics Routing, Settings, Upload/Download, and Firmware. The main content area is titled 'MODBUS MASTER SETTINGS' and includes sections for 'MASTER ENABLE', 'MASTER MESSAGE SELECT', and 'Master Message' configuration.

MODBUS MASTER SETTINGS

Save Settings Discard Changes Set Defaults

MASTER ENABLE

Ethernet master enabled: No
RS485 master enabled: No

MASTER MESSAGE SELECT

Next Previous Jump to 0

Master Message

Message #0

Message enabled: No
Device address: 0
Function: Not configured
Register address: 0
Number of registers: 0
Interface to use: Not configured
Transmit interval: 0
Forward received data to: Default target
Received data number: 0
Data source for writes: Default source
Source data number: 0

<configured ip>/diagnostics_routing.shtml

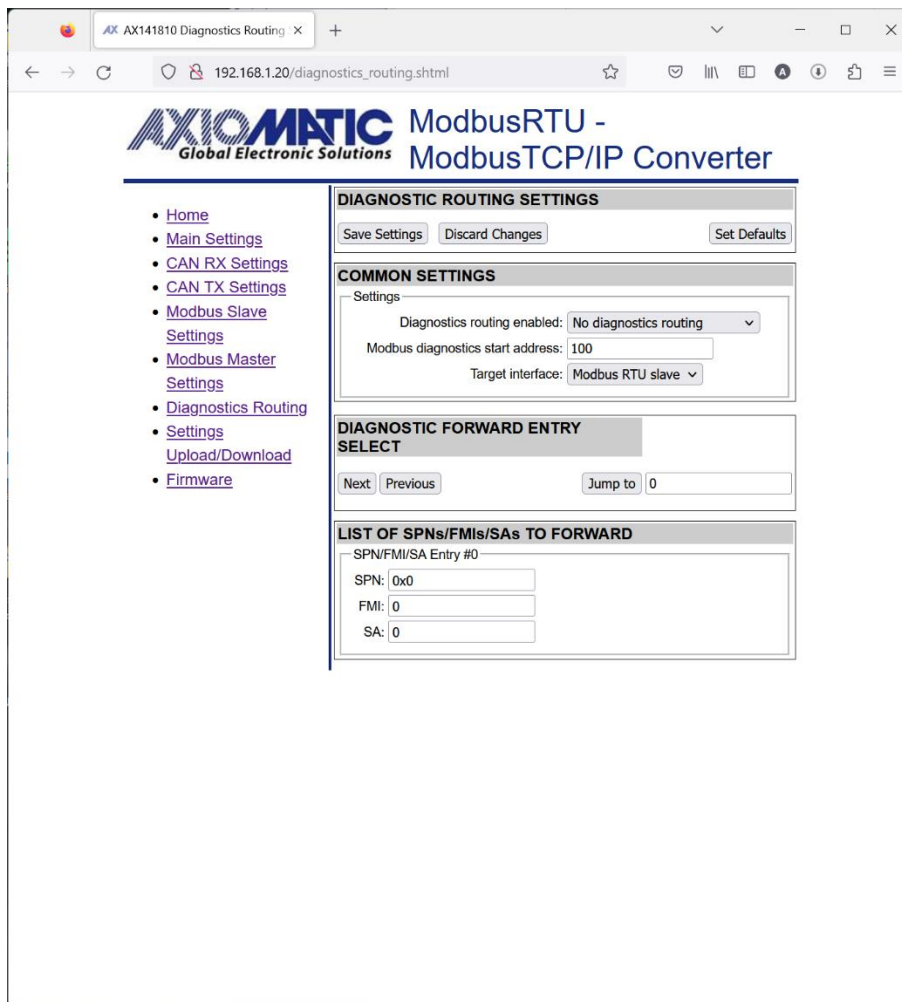
J1939 DM1 diagnostics frames can be routed to Modbus slave interfaces (either RTU or TCP/IP) using the Diagnostics routing configuration.

The routing options include routing all received diagnostics to Modbus or only routing the specified ones.

In case specified diagnostics routing is configured, the SPN is the main parameter to configure. The diagnostics are filtered using this setting. In case needed, the FMI and SA values can be used for more detailed filtering of the received DM1 frames. The FMI and SA can be set to “don’t care” values (32 for FMI and 255 for SA) for accepting a wider range of SPNs.

The received DM1 data is forwarded to Modbus slave holding registers using this data layout.

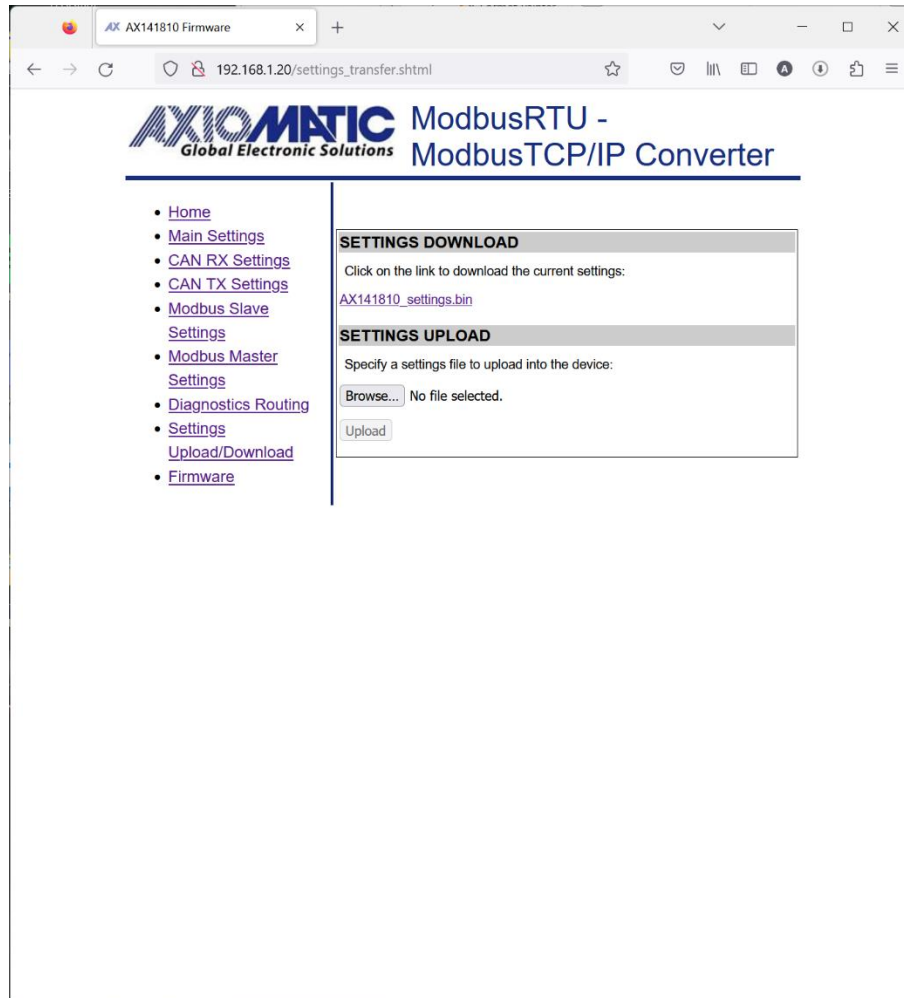
| | Holding register | |
|----------------------------|------------------|------------|
| | <15:8> | <7:0> |
| <MB diag. start addr.> | | SPN (MSBs) |
| <MB diag. start addr. + 1> | SPN (16 LSBs) | |
| <MB diag. start addr. + 2> | Lamp | FMI |
| <MB diag. start addr. + 3> | SA | OC |



<configured ip>/settings_transfer.shtml

The settings can be downloaded from the RS485-MODBUS-ENET as a binary file. When a settings file is uploaded to the RS485-MODBUS-ENET, the settings are checked using a CRC32 checksum. In case the checksum isn't correct, the uploaded settings won't be stored to RS485-MODBUS-ENET's non-volatile memory.

Please also note that AX141810A and AX141830A settings are not compatible with each other due to different number of supported routing functions.



5.2. Ethernet Parameter Setpoints

The main Ethernet parameters can be configured using EA for easier initial configuration of the RS485-MODBUS-ENET device. A power cycle is needed for taking the new settings into use.

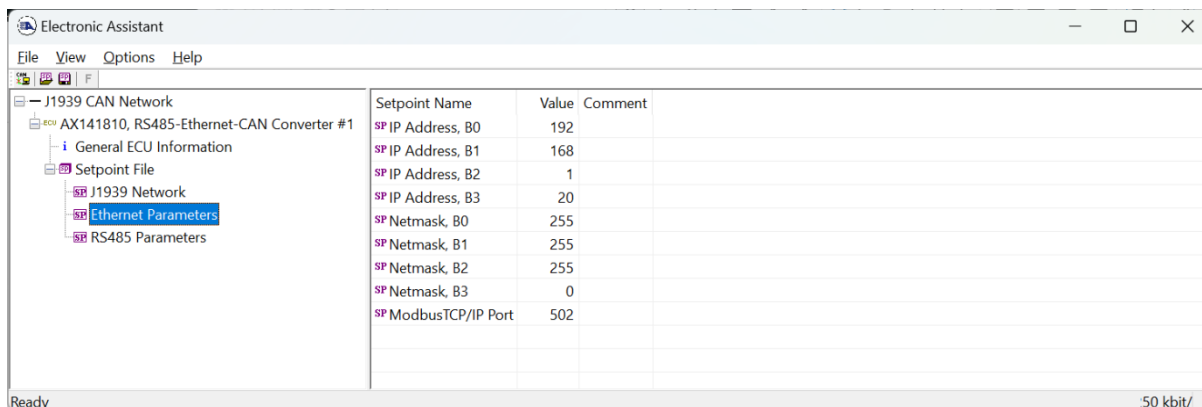


Figure 4 – Screen Capture of Ethernet Parameter Setpoints

| Name | Range | Default | Notes |
|-------------------|-----------|---------|--|
| IP Address, B0 | 0...255 | 192 | These settings define an IP address: 192.168.1.20 |
| IP Address, B1 | 0...255 | 168 | |
| IP Address, B2 | 0...255 | 1 | |
| IP Address, B3 | 0...255 | 20 | |
| Netmask, B0 | 0...255 | 255 | These settings define a netmask 255.255.255.0 |
| Netmask, B1 | 0...255 | 255 | |
| Netmask, B2 | 0...255 | 255 | |
| Netmask, B3 | 0...255 | 0 | |
| ModbusTCP/IP Port | 0...65535 | 502 | The port for accessing the Modbus slave interface. |

Table 3 – Ethernet Parameter Setpoints

5.3. RS485 Parameter Setpoints

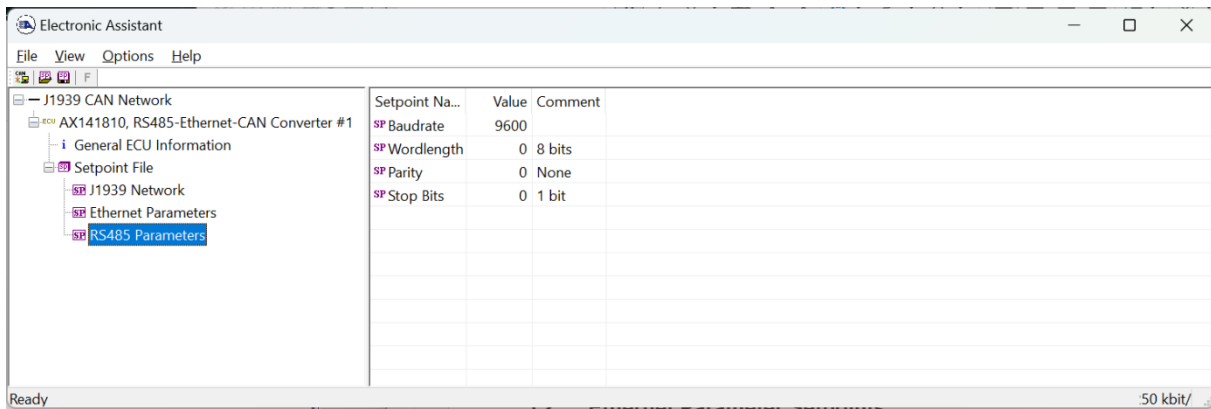


Figure 5 – Screen Capture of RS485 Parameter Setpoints

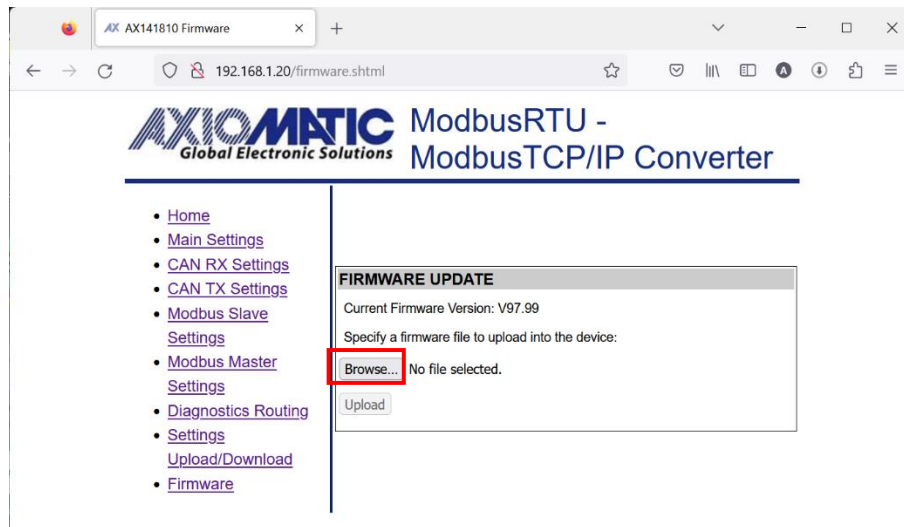
| Name | Range | Default | Notes |
|------------|------------|------------|---|
| Baudrate | 0...256000 | 9600 | The RS485 port baud rate to use. |
| Wordlength | 0, 1 | 0 – 8 bits | Number of data bits to use, 8bits or 9bits. |
| Parity | 0, 1, 2 | 0 – None | Parity: None, even, odd. |
| Stop bits | 0, 1 | 0 – 1 bit | Number of stop bits, 1 bit or 2 bits. |

Table 4 – RS485 Parameter Setpoints

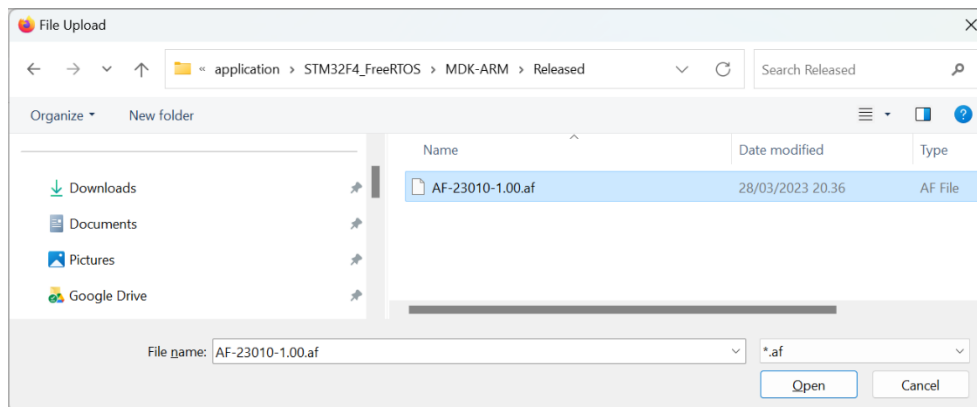
6. REFLASHING OVER ETHERNET USING A WEB BROWSER

The AX141810A/AX141830A can be upgraded with new application firmware using a web browser. Once the correct configuration password is entered, the firmware reflash can be done using the 'Firmware' page.

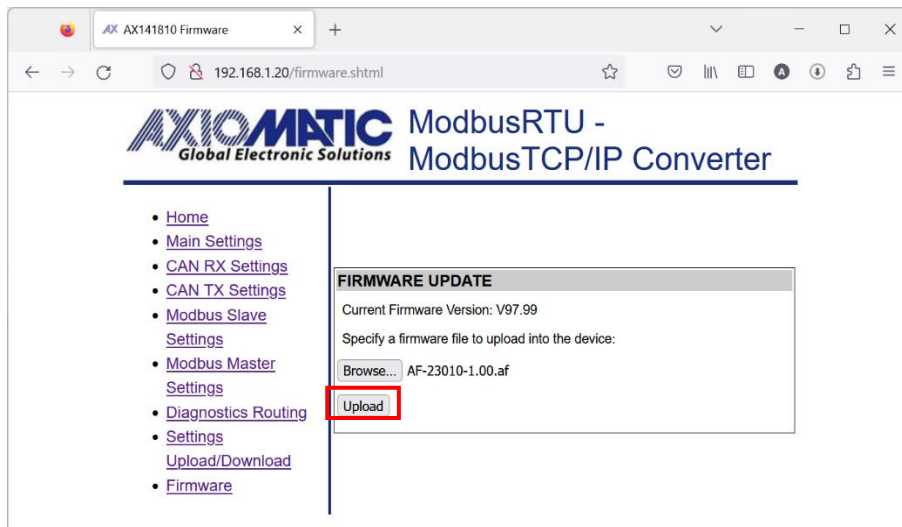
<configured ip>/firmware.shtml



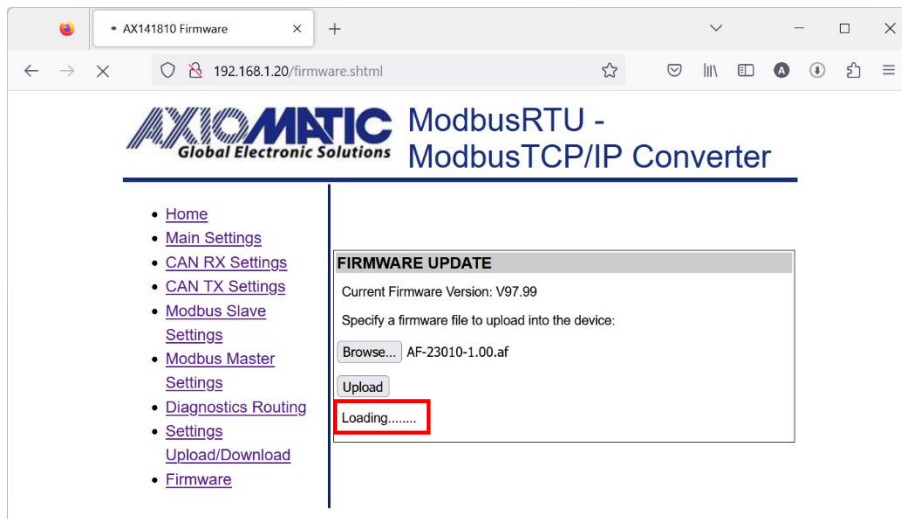
On the 'Firmware' page, a file selection dialog can be opened by pressing the 'Browse...' button.



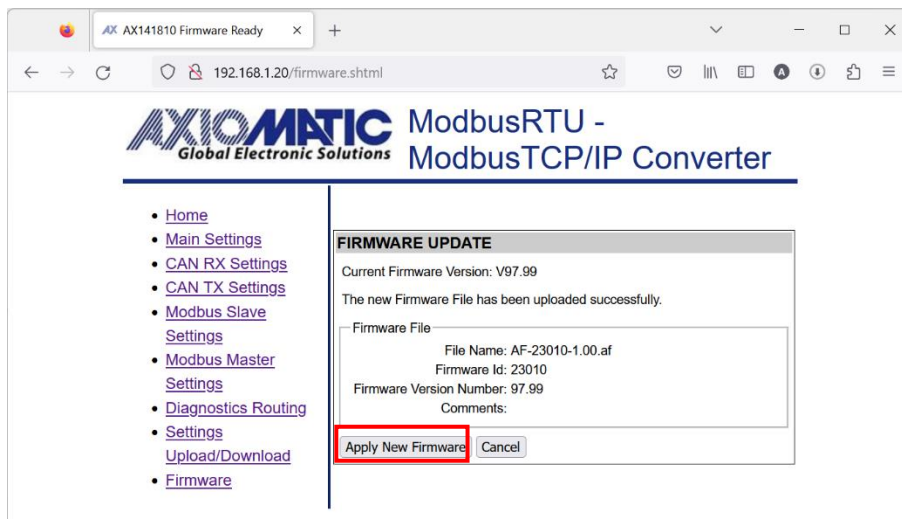
Navigate to where you had saved the **AF-23010-x.xx.af** file sent from Axiomatic. (Note: only binary (.af) files can be flashed using the web browser firmware update interface.)



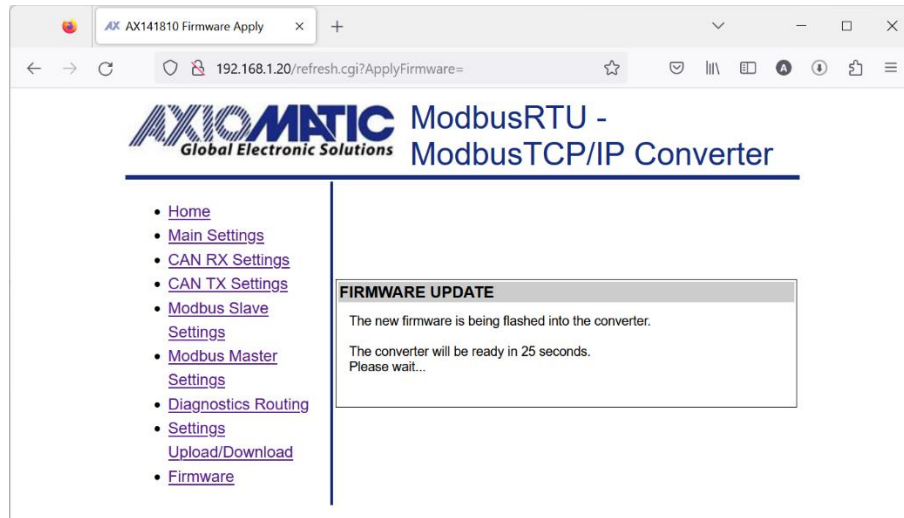
Once the file is selected, the actual upload/upgrade process is started by pressing the 'Upload' button.



The firmware upload process is shown below the 'Upload' button.



Once the upload is finished and the file checked and stored to a temporary location on the AX141810A/AX141830A, the user is prompted to either to 'Apply New Firmware' or cancel the operation.



The firmware reflash procedure takes 30 seconds to finish. After this the AX141810A/AX141830A reboots automatically to the new firmware and returns to the password dialog.

APPENDIX A - TECHNICAL SPECIFICATION

Specifications are indicative and subject to change. Actual performance will vary depending on the application and operating conditions. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process as described on <https://www.axiomatic.com/service/>.

Note: All specifications are typical at nominal input voltage and 25°C unless otherwise specified.

Power

| | |
|-----------------------------|-------------------------------------|
| Power Supply Input | 12 or 24 VDC nominal (9 to 36 VDC) |
| Quiescent Current | 130 mA @ 12 V; 70 mA @ 24 V typical |
| Surge Protection | 95 VDC |
| Under-Voltage Protection | Hardware shutdown at 6 VDC |
| Over-Voltage Protection | Hardware shutdown at 42 VDC |
| Reverse Polarity Protection | Provided up to -40 V |

Functionality

| | |
|---------------------|--|
| Conversion Platform | <p>The Protocol Converter supports conversion logic for bi-directional data exchange between Ethernet (Modbus TCP/IP), RS-485 (Modbus RTU) and SAE J1939 CAN networks.</p> <p>The actual conversion logic setup is highly application specific. The two firmware versions, AX141810A and AX141830A both support the same data routing functions. The difference is in the amount of routing rules and message definitions.</p> <p>The AX141810A is a general-purpose device with support for both directions, Modbus (RTU+TCP/IP) to CAN and vice versa. The AX141810A ships with no configuration to allow the user to set up the parameters.</p> <p>The AX141830A is targeted mainly for CAN to Modbus (RTU+TCP/IP) direction.</p> |
| Ethernet | <p>1 port 10/100 Mbit Ethernet compliant 10BASE-T, 100BASE-Tx (auto-negotiation and full-duplex supported) Auto-MDIX Modbus TCP/IP</p> |
| RS-485 | <p>Modbus RTU Isolated 1 half-duplex RS-485 port provided Baud rate: Configurable (75 bit/s to 256 kbit/s)</p> |
| CAN | <p>SAE J1939 port Isolated Baud rate: 250 kbit/s (default) 250 kbit/s, 500 kbit/s, 1 Mbit/s auto-baud-rate detection</p> |

General Specifications

| | |
|-----------------|---|
| Microcontroller | |
| Isolation | <p>CAN isolation: 330 Vrms RS-485 isolation: 300 Vrms</p> |
| User Interface | <p>Parameters are configurable using a web browser.</p> <p>Axiomatic Electronic Assistant (P/N: AX070502 or AX070506K) can be used for configuring device IP address, netmask, and Modbus port.</p> <p>Firmware can be updated using a web browser</p> |
| Compliance | RoHS |
| Vibration | |
| Shock | |

| Operating Conditions | -40 to 65°C (-40 to 149°F) | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--------------------------|--|-----------------------|--|-------|-------------|---|-------|---|--------------|---|--------------|---|---------------|---|--------|---|-------|---|-------|---|-----------|---|---------------|----|--------------|----|--------------|----|-------|
| Storage Temperature | -40 to 105°C (-40 to 221°F) | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Weight | 0.70 lbs. (0.32 kg) | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Protection | IP67 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Enclosure and Dimensions | Aluminum enclosure Integral TE Deutsch equivalent connector Encapsulation Refer to dimensional drawing. | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Electrical Connections | <p>12-pin TE Deutsch equivalent connector P/N: DT15-12PA A mating plug KIT is available as Axiomatic P/N: AX070105.</p> <table border="1"> <thead> <tr> <th colspan="2">CAN and I/O Connector</th> </tr> <tr> <th>Pin #</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>BATT-</td> </tr> <tr> <td>2</td> <td>Ethernet TX+</td> </tr> <tr> <td>3</td> <td>Ethernet RX+</td> </tr> <tr> <td>4</td> <td>RS485_TX+/RX+</td> </tr> <tr> <td>5</td> <td>CAN_SH</td> </tr> <tr> <td>6</td> <td>CAN_H</td> </tr> <tr> <td>7</td> <td>CAN_L</td> </tr> <tr> <td>8</td> <td>RS485_GND</td> </tr> <tr> <td>9</td> <td>RS485_TX-/RX-</td> </tr> <tr> <td>10</td> <td>Ethernet RX-</td> </tr> <tr> <td>11</td> <td>Ethernet TX-</td> </tr> <tr> <td>12</td> <td>BATT+</td> </tr> </tbody> </table> | CAN and I/O Connector | | Pin # | Description | 1 | BATT- | 2 | Ethernet TX+ | 3 | Ethernet RX+ | 4 | RS485_TX+/RX+ | 5 | CAN_SH | 6 | CAN_H | 7 | CAN_L | 8 | RS485_GND | 9 | RS485_TX-/RX- | 10 | Ethernet RX- | 11 | Ethernet TX- | 12 | BATT+ |
| CAN and I/O Connector | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Pin # | Description | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | BATT- | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Ethernet TX+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | Ethernet RX+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | RS485_TX+/RX+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | CAN_SH | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | CAN_H | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | CAN_L | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | RS485_GND | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 9 | RS485_TX-/RX- | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 10 | Ethernet RX- | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 11 | Ethernet TX- | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 12 | BATT+ | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Mounting | <p>Mounting holes sized for #10 or M4.5 bolts. The bolt length will be determined by the end-user's mounting plate thickness. The mounting flange of the controller is 0.19 inches (4.75 mm) thick.</p> <p>If the module is mounted without an enclosure, it should be mounted to reduce the likelihood of moisture entry. Install the unit with appropriate space available for servicing and for adequate wire harness access (6 inches or 15 cm) and strain relief (12 inches or 30 cm).</p> <p>The CAN wiring is considered intrinsically safe. The power wires are not considered intrinsically safe and so in hazardous locations, they need to be located in conduit or conduit trays at all times. The module must be mounted in an enclosure in hazardous locations for this purpose.</p> <p>All field wiring should be suitable for the operating temperature range of the module.</p> <p>All chassis grounding should go to a single ground point designated for the machine and all related equipment.</p> | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

OUR PRODUCTS

AC/DC Power Supplies
Actuator Controls/Interfaces
Automotive Ethernet Interfaces
Battery Chargers
CAN Controls, Routers, Repeaters
CAN/WiFi, CAN/Bluetooth, Routers
Current/Voltage/PWM Converters
DC/DC Power Converters
Engine Temperature Scanners
Ethernet/CAN Converters,
Gateways, Switches
Fan Drive Controllers
Gateways, CAN/Modbus, RS-232
Gyroscopes, Inclinometers
Hydraulic Valve Controllers
Inclinometers, Triaxial
I/O Controls
LVDT Signal Converters
Machine Controls
Modbus, RS-422, RS-485 Controls
Motor Controls, Inverters
Power Supplies, DC/DC, AC/DC
PWM Signal Converters/Isolators
Resolver Signal Conditioners
Service Tools
Signal Conditioners, Converters
Strain Gauge CAN Controls
Surge Suppressors

OUR COMPANY

Axiomatic provides electronic machine control components to the off-highway, commercial vehicle, electric vehicle, power generator set, material handling, renewable energy and industrial OEM markets. ***We innovate with engineered and off-the-shelf machine controls that add value for our customers.***

QUALITY DESIGN AND MANUFACTURING

We have an ISO9001:2015 registered design/manufacturing facility in Canada.

WARRANTY, APPLICATION APPROVALS/LIMITATIONS

Axiomatic Technologies Corporation reserves the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process at <https://www.axiomatic.com/service/>.

COMPLIANCE

Product compliance details can be found in the product literature and/or on axiomatic.com. Any inquiries should be sent to sales@axiomatic.com.

SAFE USE

All products should be serviced by Axiomatic. Do not open the product and perform the service yourself.



This product can expose you to chemicals which are known in the State of California, USA to cause cancer and reproductive harm. For more information go to www.P65Warnings.ca.gov.

SERVICE

All products to be returned to Axiomatic require a Return Materials Authorization Number (RMA#) from rma@axiomatic.com. Please provide the following information when requesting an RMA number:

- Serial number, part number
- Runtime hours, description of problem
- Wiring set up diagram, application and other comments as needed

DISPOSAL

Axiomatic products are electronic waste. Please follow your local environmental waste and recycling laws, regulations and policies for safe disposal or recycling of electronic waste.

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