

TECHNICAL DATASHEET #TDAX100271 UNIVERSAL MOTOR CONTROLLER, 100W

*Up to 4 Universal Signal Inputs, SENT Inputs
3 Encoder Inputs or PWM Outputs
2 +5V, 200 mA Reference Voltages
1 BLDC or 2 Bidirectional Brushed DC Motor Control Outputs up to 6A
Sensorless or Hall Effect Sensor Feedback
CAN (CANopen®)
P/N: AX100271*

Description: The universal motor controller, 100W, drives a brushed DC Motor up to 6A or a 3-phase BLDC motor up to 6A. It features a CANopen® ports. Interfacing with 12V or 24Vdc power, the controller accepts 4 universal inputs (voltage, current, Frequency, PWM, SENT or digital input types). Hall sensor feedback input is accepted. In addition, the controller interfaces with 3 standard A and B phase encoder inputs or can provide 3 PWM signal outputs. Settings are user configurable to suit many applications. The controller is packaged in an enclosure which is a TE Deutsch P/N equivalent and features a 24-pin connector.



Applications:

Typical applications can include test stands; and industrial automation.

Features:

- Drives up to 2 bidirectional brushed DC Motors up to 6A (2 bidirectional full bridge outputs)
- Or can drive a BLDC Motor, 3 Phase, up to 6A (a half-bridge output with sensorless or Hall Effect sensor operation)
- Four (4) Universal Signal Inputs are user selectable:
 - Analog (0-5V, 0-10V, 4-20 mA or 0-20 mA);
 - Digital;
 - SENT;
 - PWM;
 - or Frequency signal types.
- Provides 2 +5V, 200 mA reference voltages to power devices
- Three (3) encoder inputs or one Quadrature encoder input and one PWM input are accepted. Alternatively, 3 PWM outputs can be provided.
- Robust 6...36Vdc power supply interface with reverse polarity protection
- Reverse polarity, under and overvoltage protection provided
- Operational from -40 to 85°C (-40 to 185°F)
- CANopen® port permits networking
- EDS File
- An enclosure and connectors which are TE Deutsch equivalents.

Ordering Part Numbers:

CANopen® Controller: AX100271
EDS File

Accessories:

PL-DTM06-12SA-12SB Mating Plug Kit (1 DTM06-12S, DTM06-12SB, 2 W12S, 24 contacts)

Block Diagram:

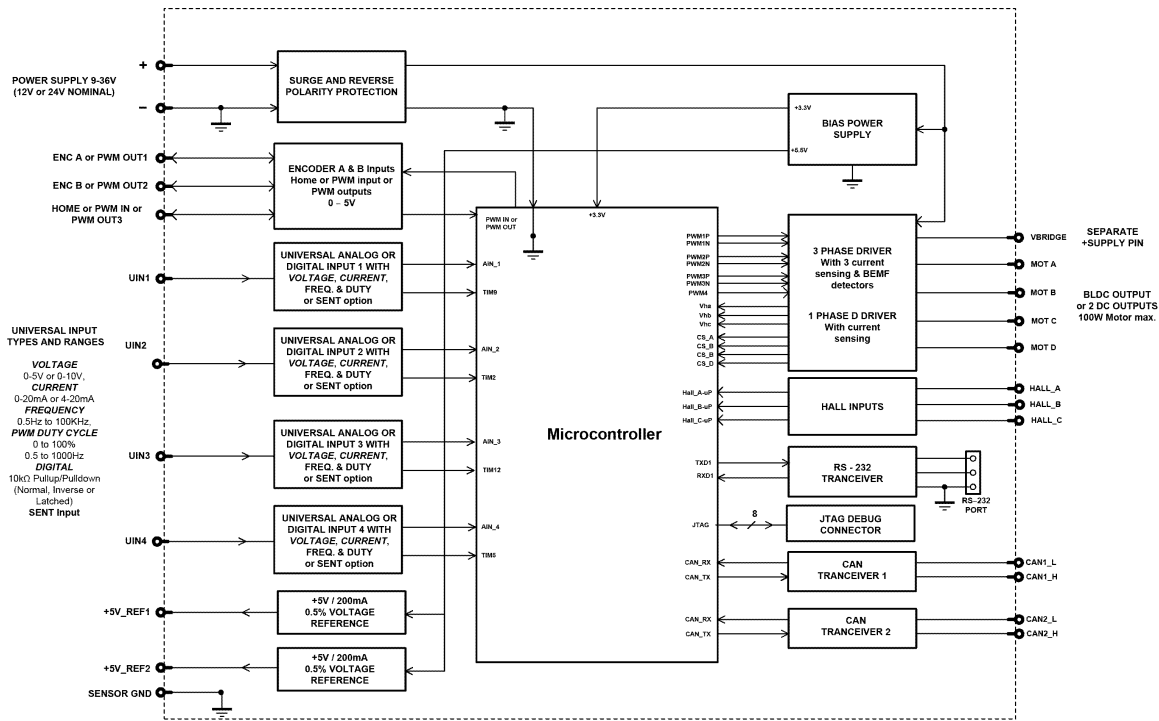


Figure 1.0 Block Diagram

Technical Specifications:

Specifications are indicative and subject to change. Actual performance will vary depending on the application and operating conditions. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process as described on <https://www.axiomatic.com/service/>.

Input Specifications (Refer to the block diagram.)

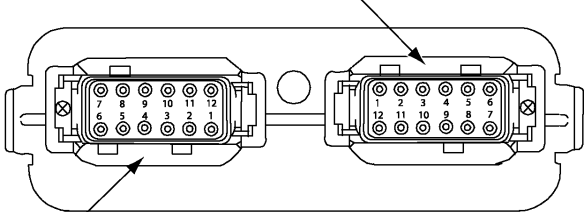
Power Supply Input	12 or 24Vdc nominal (6...36 Vdc power supply range) NB. The maximum total current draw permitted on the power supply input pins is 7.5 Amps @ 24Vdc, at one time.
Reverse Polarity Protection	Provided up to -80Vdc
Surge and Transient Protection	Provided
Under-voltage Protection	Provided (hardware shutdown at 6V)
Overvoltage Protection	Provided (hardware shutdown at 41V)
Universal Signal Inputs	Up to 4 inputs are selectable by the user from the following. <ul style="list-style-type: none"> Analog Voltage (0-5V, 0-10V), Current (0-20 mA, 4-20mA, 249Ω current sense resistor) Frequency or PWM Inputs Digital Or SENT (option). 12-bit Analog to Digital resolution Amplitude up to +Vsupply Protected against shorts to GND. See Tables 1 and 2. NB.SAE J2716 SENT (Single Edge Nibble Transmission) protocol is a point-to-point scheme for transmitting signal values from a sensor to a controller.

Encoder Inputs	Three (3) Standard A and B and Home phase encoder inputs Alternatively, one PWM input and one Quadrature Encoder input can be selected. Frequency Range: 0-250 kHz Amplitude: 0-5Vdc This feature is user configurable as PWM Outputs (see Output section).																																												
Hall Sensor	Standard open collector/drain HALL EFFECT Sensor Input type (3) 1K Pull-up to +5V per input is provided.																																												
Minimum and Maximum Ratings	<table border="1"> <thead> <tr> <th colspan="4">Table 1.0. Absolute Maximum and Minimum Ratings</th> </tr> <tr> <th>Characteristic</th> <th>Min</th> <th>Max</th> <th>Units</th> </tr> </thead> <tbody> <tr> <td>Power Supply</td> <td>6</td> <td>36</td> <td>V dc</td> </tr> <tr> <td>Voltage Input</td> <td>0</td> <td>36</td> <td>V dc</td> </tr> <tr> <td>Current Input</td> <td>0</td> <td>21</td> <td>mA</td> </tr> <tr> <td>Current Input – Voltage Level</td> <td>0</td> <td>12</td> <td>Vdc</td> </tr> <tr> <td>Digital Type Input – Voltage Level</td> <td>0</td> <td>36</td> <td>Vdc</td> </tr> <tr> <td>PWM Duty Cycle</td> <td>0</td> <td>100</td> <td>%</td> </tr> <tr> <td>PWM Frequency</td> <td>50</td> <td>1 000</td> <td>Hz</td> </tr> <tr> <td>PWM Voltage pk - pk</td> <td>0</td> <td>36</td> <td>V dc</td> </tr> <tr> <td>Frequency</td> <td>50</td> <td>10 000</td> <td>Hz</td> </tr> </tbody> </table>	Table 1.0. Absolute Maximum and Minimum Ratings				Characteristic	Min	Max	Units	Power Supply	6	36	V dc	Voltage Input	0	36	V dc	Current Input	0	21	mA	Current Input – Voltage Level	0	12	Vdc	Digital Type Input – Voltage Level	0	36	Vdc	PWM Duty Cycle	0	100	%	PWM Frequency	50	1 000	Hz	PWM Voltage pk - pk	0	36	V dc	Frequency	50	10 000	Hz
Table 1.0. Absolute Maximum and Minimum Ratings																																													
Characteristic	Min	Max	Units																																										
Power Supply	6	36	V dc																																										
Voltage Input	0	36	V dc																																										
Current Input	0	21	mA																																										
Current Input – Voltage Level	0	12	Vdc																																										
Digital Type Input – Voltage Level	0	36	Vdc																																										
PWM Duty Cycle	0	100	%																																										
PWM Frequency	50	1 000	Hz																																										
PWM Voltage pk - pk	0	36	V dc																																										
Frequency	50	10 000	Hz																																										
Input Accuracy and Resolution	<table border="1"> <thead> <tr> <th colspan="3">Table 2.0. Input Accuracy</th> </tr> <tr> <th>Input Type</th> <th>Accuracy</th> <th>Resolution</th> </tr> </thead> <tbody> <tr> <td>Voltage</td> <td>+/- 1%</td> <td>1 [mV]</td> </tr> <tr> <td>Current</td> <td>+/- 1%</td> <td>1 [uA]</td> </tr> <tr> <td>PWM</td> <td>+/- 1%</td> <td>0.1 [%]</td> </tr> <tr> <td>Frequency</td> <td>+/- 1%</td> <td>0.01 [Hz]</td> </tr> </tbody> </table>	Table 2.0. Input Accuracy			Input Type	Accuracy	Resolution	Voltage	+/- 1%	1 [mV]	Current	+/- 1%	1 [uA]	PWM	+/- 1%	0.1 [%]	Frequency	+/- 1%	0.01 [Hz]																										
Table 2.0. Input Accuracy																																													
Input Type	Accuracy	Resolution																																											
Voltage	+/- 1%	1 [mV]																																											
Current	+/- 1%	1 [uA]																																											
PWM	+/- 1%	0.1 [%]																																											
Frequency	+/- 1%	0.01 [Hz]																																											
Analog Ground	One sensor ground connection is provided.																																												
Reference Voltages	2 +5V, 200 mA maximum Regulation at +/-0.5% accuracy is provided.																																												

Output Specifications

Outputs	Two outputs for a bidirectional Brushed DC Motor, up to 6A <ul style="list-style-type: none"> Two bidirectional full bridge outputs Or One output for a BLDC Motor, up to 6A <ul style="list-style-type: none"> One 3-phase half-bridge output, current sensing per each phase Sensorless or HALL Effect Sensor operation 6A nominal current output (100W) NB. The maximum total current draw permitted on the power supply input pins is 7.5 Amps @ 24Vdc, at one time.
V Bridge Connection	Separate +Vsupply connection for motor outputs
PWM Outputs	Up to 3 independent PWM outputs (available if 3 encoder inputs option is not selected) PWM Frequency: 0-250 kHz Duty Cycle: 0 to 100% Amplitude: 5V @ 30 mA
Output Accuracy	PWM outputs +/-0.1%
Protection	Overcurrent protection is provided on all outputs. It is programmable.

General Specifications

Operating Conditions	-40 to 85°C (-40 to 185°F)
Weight	0.60 lb. (0.272 kg)
Protection	IP65; Unit is conformal coated within the housing.
Microprocessor	STM32F407VGT7
Quiescent Current Draw	45 mA @ 24Vdc Typical; 73 mA @ 12Vdc Typical
CAN Interface	1 CAN port (CANopen®)
Network Termination	It is necessary to terminate the network with external termination resistors. The resistors are 120 Ohm, 0.25W minimum, metal film or similar type. They should be placed between CAN_H and CAN_L terminals at both ends of the network.
Control Logic	Standard embedded software is provided.
User Interface	EDS File Standard CANopen® tools not provided
Software Flashing	Use the Axiomatic Electronic Assistant KIT, P/Ns: AX070502, or AX070506K
Electrical Connections	<p>Refer to Table 3.0. 24-pin receptacle (equivalent TE Deutsch P/N: DTM13-12PA-12PB-R008) Mating plugs kits are available on request and is equivalent to the TE Deutsch P/Ns: DTM06-12SA and DTM06-12SB with 2 wedgelocks (WM12S), and 24 contacts (0462-201-20141). 20 AWG wire is recommended for use with contacts 0462-201-20141.</p> <p style="text-align: center;">Key Arrangement B (black)</p>  <p style="text-align: center;">Key Arrangement A (grey)</p> <p style="text-align: center;">FRONT VIEW 24 PIN RECEPTACLE</p>
Enclosure and Dimensions	High Temperature Nylon PCB Enclosure - (equivalent TE Deutsch P/N: EEC-325X4B) Refer to Figure 2.0.

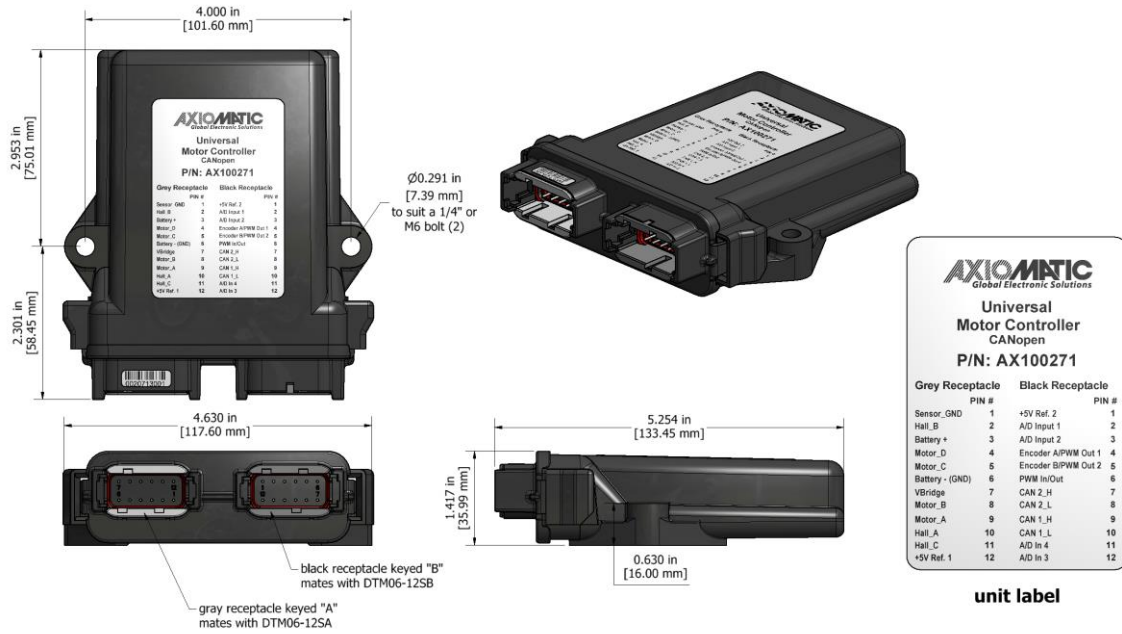


Figure 2.0 - Dimensional Drawing

Table 3.0 – Pin out: AX100270

Grey Connector PIN #	Function	Black Connector PIN #	Function
1	Sensor GND	1	+5V Reference 2
2	Hall B	2	A/D Input 1
3	Battery +	3	A/D Input 2
4	Motor D	4	Encoder A/PWM Out 1
5	Motor C	5	Encoder B/PWM Out 2
6	Battery - (GND)	6	PWM In/Out
7	V Bridge	7	NOT USED
8	Motor B	8	NOT USED
9	Motor A	9	CAN 1_H
10	Hall A	10	CAN 1_L
11	Hall C	11	A/D Input 4
12	+5V Reference 1	12	A/D Input 3

CANopen® is a registered community trademark of CAN in Automation e.V.

Form: TDAX100271-01/01/2024