

TECHNICAL DATASHEET #TDAX020410A 12 INPUT, 12 OUTPUT VALVE CONTROLLER

> 7 Universal Signal and 5 Digital Inputs 8-2.5A Proportional and 4-3A On/Off Outputs 1 +5V, 100 mA Reference Voltage CAN (SAE J1939) with Axiomatic Electronic Assistant P/N: AX020410A

## Features:

- 6 Universal Signal Inputs are user configurable as:
  - o 0-5V, 0-10V, 4-20mA or 0-20mA
  - $\circ$  20 $\Omega$  to 250 k $\Omega$  Resistive
  - 1 Hz to 10 kHz PWM
  - Digital
  - Three of the inputs can be configured as a pulse counter.
- 1 Signal Input is user configurable as:
  - o 0-5V, 0-10V, 4-20mA or 0-20mA
  - o 1 Hz to 10 kHz PWM
  - o Digital
  - Pulse Counter
- 5 PWM/Digital Inputs are user configurable as:
  - o 1 Hz to 10 kHz PWM
  - o Active High/Active Low Digital
  - Three of the inputs can be configured as a pulse counter.
- 8 Outputs (0...2.5A) drive proportional poppet or spool or On/Off hydraulic valves and are user selectable as:
  - o Proportional Current
  - Hotshot Digital
  - PWM Duty Cycle
  - Proportional Voltage
  - o On/Off Digital
- 4 Outputs (3A) to drive ON/OFF hydraulic valves
- 1 SAE J1939 CAN bus port
- 12V or 24Vdc nominal power
- Surge, transient, reverse polarity, overvoltage, undervoltage and short circuit protections
- -40 to +85 °C operating temperature
- Designed for EMC compliance, CE marking
- 48-pin housing and connectors (TE Deutsch equivalents)
- IP67 rating
- Vibration compliant
- Configurable with the Axiomatic Electronic Assistant

## **Applications:**

- Oil and Gas Equipment Automation
- Off-highway Machine Automation
- Agricultural Equipment

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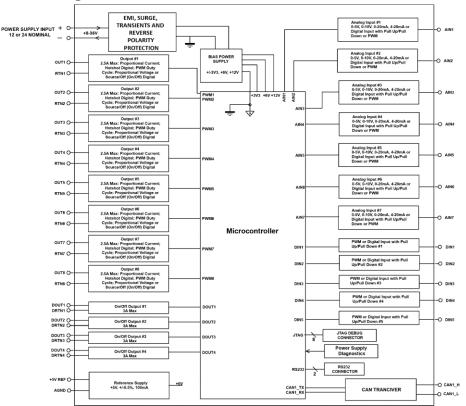


### **Ordering Part Numbers:**

Controller, SAE J1939, auto-baud-rate detect: **AX020410A** Controller, CANopen®: **AX020411A** Accessories: Mating Plug Kit: **AX070123** Axiomatic Electronic Assistant Configuration KIT: **AX070502, AX070505K** or **AX070506K** 

**Description:** The valve controller provides precise, repeatable control of 8 proportional or on/off solenoids plus 4 on/off solenoids. It is networked on a SAE J1939 bus. Up to 7 signal inputs and 5 digital inputs are accepted for interface to a PLC, Engine Control Module, switches, command potentiometers or sensors. The controller has altogether twelve inputs, which are divided into Universal and Digital Inputs. Universal Inputs can be configured to measure voltage, current or digital signal and Digital Inputs can be configured to measure voltage, current or digital signal and Digital Inputs can be configured to measure voltage, current or digital signal and Digital Inputs can be configured to measure digital signals. In addition, Universal Inputs 1 to 6 can be configured to measure resistance. Frequency, signal pulse width and pulse count can be measured with Universal Inputs 1, 3, 5, 7 and Digital Inputs 1, 3, 5. It operates with 12Vdc or 24Vdc power. Designed for rugged machine applications, it features an IP67 rating, CE marking and is suitable for high vibration installations. Controller settings are user configuration tool and an USB-CAN converter. From the control logic perspective, the AX020410 consists of a set of internal functional blocks, which can be individually configured. The AX020410 model takes a simpler approach suitable for most applications rather than the more complex control logic found in the AX020400 model. For more details on control logic, refer to the User Manual.

# Block Diagram:



#### **Technical Specifications:**

Specifications are indicative and subject to change. Actual performance will vary depending on the application and operating conditions. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process as described on <a href="https://www.axiomatic.com/service/">https://www.axiomatic.com/service/</a>

#### **Input Specifications:**

TDAX020410A

Power Supply Input	12 or 24Vdc nominal (836 Vdc power supply range) NB. The maximum total current draw permitted on the power supply input pins is 15 Amps @ 24Vdc, at one time. Suitable for engine cranking and load dump				
Reverse Polarity Protection	Provided up to -80Vdc				
Surge, Transient Protection	Provided up to -solvac				
Under-voltage Protection	Provided (hardware shutdown)				
Overvoltage Protection	Provided (hardware shutdown) Provided (hardware shutdown)				
<u>0</u>					
All Inputs	Up to 12 inputs are selectable by the user from the following. <ul> <li>7 Universal Signal Inputs</li> <li>5 PWM/Digital Inputs</li> </ul> <li>All inputs, except for frequency and counter, are sampled every 10ms.</li>				
Universal Signal Input Configuration	<ul> <li>Inputs 1 through 6 are configurable as the following.</li> <li>Disable Input</li> <li>12-bit Analog to Digital (05Vdc, 010Vdc) (420mA or 020mA, Current sense resistor 124Ω) (20Ω to 250 kΩ Resistive)</li> <li>Digital input (Active High to Vps or Active Low to GND, Amplitude 3.3V to +Vps, Configurable pull up or pull down resistor)</li> <li>In addition, inputs 1, 3 and 5 are configurable as the following.</li> <li>PWM Signal</li> </ul>				
	(Frequency: 1-10,000 Hz • Pulse Counter	, 0-100%	6 D.C., 1MΩ	impedance	e)
Signal Input 7 Configuration	<ul> <li>Input 7 is configurable as the following.</li> <li>Disable Input (No CAN messages associated with that channel are sent.)</li> <li>12-bit Analog to Digital (05Vdc, 010Vdc) (420mA or 020mA, Current sense resistor 124Ω)</li> <li>PWM Signal (Frequency: 1-10,000 Hz, 0-100% D.C., 1MΩ impedance)</li> <li>Pulse Counter</li> <li>Digital input (Active High to Vps or Active Low to GND, Amplitude 3.3V to +Vps, Configurable pull up or pull down resistor)</li> </ul>				
PWM/Digital Input Configuration	<ul> <li>PWM/Digital Inputs 1 through 5 are configurable as the following.</li> <li>Disable input (No CAN messages associated with that channel are sent.)</li> <li>Digital input (Active High to Vps or Active Low to GND, Amplitude 3.3V to +Vps, Configurable pull up or pull down resistor)</li> <li>In addition, inputs 1, 3 and 5 are configurable as the following.</li> <li>PWM Signal (Frequency: 1-10,000 Hz, 0-100% D.C., 1MΩ impedance)</li> <li>Pulse counter</li> </ul>				
Minimum and Maximum	Table 1.0. Absolute Maximum	and Mir	nimum Ratin	as	]
Ratings	Characteristic	Min	Max	Units	
	Power Supply	8	36	V dc	
	Voltage Input	0	36	V dc	
	Current Input	0	21	mA	
	Current Input – Voltage Level	0	36	Vdc	
	Digital Type Input – Voltage Level	0	36	Vdc	
	PWM Duty Cycle	0	100	%	
	PWM Frequency	50	10 000	Hz	
	PWM Voltage pk - pk	0	36	V dc	
	RPM Frequency	50	10 000	Hz	

Input Accuracy and Resolution	Table 2.0. Input Accu	Table 2.0. Input Accuracy		
	Input Type	Accuracy	Resolution	
	Voltage	+/- 1%	1 [mV]	
	Current	+/- 1%	1 [uA]	
	Resistive	+/- 1%	1 [Ω]	
	PWM	+/- 1% (<5kHz) +/- 2% (>5kHz)	0.01 [%]	
Grounds	7 universal signal input gro 1 PWM/digital signal grou 1 +5V reference ground			
Reference Voltages	1 +5V, 100 mA maximum Regulation at +/-0.5% acc	uracy is provided.		

#### **Output Specifications**

8 High side sourcing up to			
	Half-bridge output, current sensing, grounded load High frequency PWM (25 kHz)		
	2.5A) are user selectable as:		
	1		
	<ul> <li>Proportional Current (See Table 3.0.)</li> <li>Hotshot Digital</li> <li>PWM Duty Cycle</li> </ul>		
	Proportional Voltage		
<ul> <li>On/Off Digital (Normal, Inverse, Latched, Blinking Logic are selectable.)</li> </ul>			
Voltage outputs: 0.1V res PWM outputs: 0.1% reso Digital on/off: Sourcing fro	solution		
NB. The maximum total	current draw permitted on the power supply input pins is 15		
Amps @ 24Vdc, at one ti Table 3.0: Proportiona	me.		
Amps @ 24Vdc, at one ti	me.		
Amps @ 24Vdc, at one ti <b>Table 3.0: Proportiona</b> Adjustable Parameter Output Current	me. I Output Adjustments Description 0- Imax (2.5A)		
Amps @ 24Vdc, at one ti Table 3.0: Proportiona Adjustable Parameter	me. I Output Adjustments Description 0- Imax (2.5A) Both minimum and maximum current settings are user		
Amps @ 24Vdc, at one ti Table 3.0: Proportiona Adjustable Parameter Output Current	me. I Output Adjustments Description 0- Imax (2.5A) Both minimum and maximum current settings are user configurable. Dither adjustments are configurable for each channel.		
Amps @ 24Vdc, at one ti <b>Table 3.0: Proportiona</b> <b>Adjustable Parameter</b> Output Current Adjustments	me. IOutput Adjustments Description 0- Imax (2.5A) Both minimum and maximum current settings are user configurable. Dither adjustments are configurable for each channel. Dither Amplitude:		
Amps @ 24Vdc, at one ti <b>Table 3.0: Proportiona</b> <b>Adjustable Parameter</b> Output Current Adjustments	me. Dutput Adjustments Description 0- Imax (2.5A) Both minimum and maximum current settings are user configurable. Dither adjustments are configurable for each channel. <u>Dither Amplitude</u> : 0 mA (factory default)		
Amps @ 24Vdc, at one ti <b>Table 3.0: Proportiona</b> <b>Adjustable Parameter</b> Output Current Adjustments	me. IOutput Adjustments Description 0- Imax (2.5A) Both minimum and maximum current settings are user configurable. Dither adjustments are configurable for each channel. Dither Amplitude:		
Amps @ 24Vdc, at one ti <b>Table 3.0: Proportiona</b> <b>Adjustable Parameter</b> Output Current Adjustments	me. <b>Dutput Adjustments</b> <b>Description</b> 0- Imax (2.5A) Both minimum and maximum current settings are user configurable. Dither adjustments are configurable for each channel. <u>Dither Amplitude</u> : 0 mA (factory default) Adjustable from 0-500 mA.		
Amps @ 24Vdc, at one ti Table 3.0: Proportiona Adjustable Parameter Output Current Adjustments Superimposed Dither	me. Dutput Adjustments Description 0- Imax (2.5A) Both minimum and maximum current settings are user configurable. Dither adjustments are configurable for each channel. <u>Dither Amplitude</u> : 0 mA (factory default) Adjustable from 0-500 mA. <u>Dither Frequency</u> : 200 Hz (factory default) Adjustable from 50-400 Hz.		
Amps @ 24Vdc, at one ti <b>Table 3.0: Proportiona</b> <b>Adjustable Parameter</b> Output Current Adjustments	me.		
	Half-bridge output, curren High frequency PWM (25 Independent outputs (0 Output Disable Proportional Cu Hotshot Digital PWM Duty Cyc Proportional Vc On/Off Digital ( Current outputs: 1 mA res Voltage outputs: 0.1V res PWM outputs: 0.1% reso Digital on/off: Sourcing fro (Note: Load at supply volt		

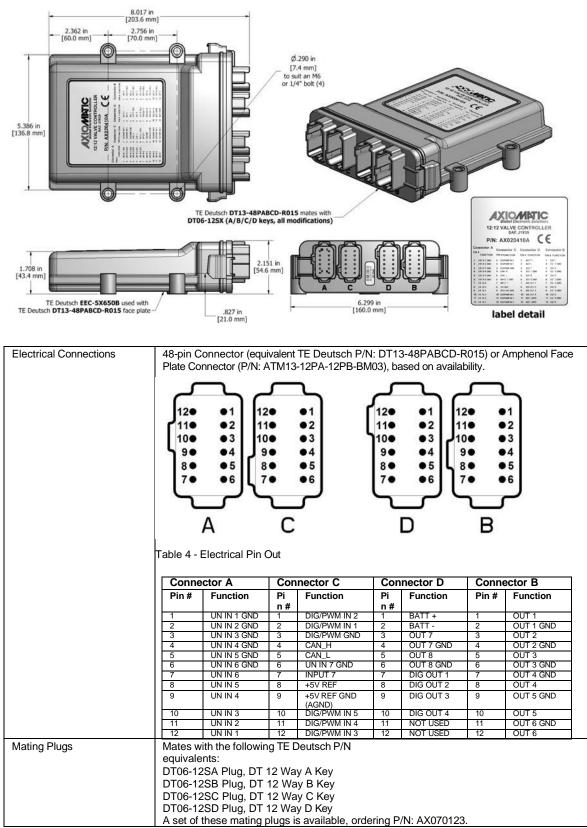
Output Accuracy	Current outputs +/-1% Voltage outputs +/- 5% PWM outputs +/-0.1%
Digital Outputs	4 High side switching outputs up to 3A (sourcing) Load current monitoring capability Fully protected Note: Outputs up to 5A are possible with a reduction in the operating temperature range.
Protection	Overcurrent protection is provided on all outputs. Short circuit protection is provided on all outputs. Overvoltage and undervoltage protection is provided on all outputs.
Error Conditions	If an error on the input is detected, the output of the controller shuts off.

## **General Specifications**

Operating Conditions	-40 to 85°C (-40 to 185°F)	
Weight	1.40 lb. (0.635 kg)	
Protection	IP67; Unit is conformal coated within the housing.	
Microprocessor	Model AX020410 - STM32F207ZG 32-bit, 1MByte flash memory Model AX020410A - STM32F427ZIT6, 2MByte flash memory, 256 KB RAM	
Quiescent Current Draw	60 mA @ 24Vdc; 81 mA @ 12Vdc	
Response Time	40 msec.	
CAN Interface	1 CAN port (SAE J1939) 250kbit/s, 500kbit/s, 667kbit/s, 1Mbit/s. Automatic Baud Rate Detection	
Network Termination	It is necessary to terminate the network with external termination resistors. The resistors are 120 Ohm, 0.25W minimum, metal film or similar type. They should be placed between CAN_H and CAN_L terminals at both ends of the network.	
Control Logic	Standard embedded software is provided and is configurable using the Axiomatic Electronic Assistant (EA). Any of the outputs can be configured to use any of the inputs either as a control signal or an enable signal as well as use the CAN network data. The user can configure the control logic using the following Function Blocks. The AX020410 model takes a simpler approach suitable for most applications rather than the more complex control logic found in the AX020400 model. For more details on control logic, refer to the User Manual.	
	<ul> <li>The Input Function Block allows the user to configure the input type. Normal, inverse and latched options are available for Universal and Digital input types. Pullup or Pull-down resistors can be enabled or disabled for Frequency, PWM or Digital Input types. Frequency/RPM or PWM input types have a Debounce setpoint to select an input capture filter. Digital inputs can be configured as Active High or Active Low. Minimum and maximum range setpoints define the range of the signal input as a control source. Input filtering is selectable.</li> <li>The Output Function Block allows for selection of each output type or output disable. Various setpoints by output type can be configured. Refer to the output specification and the user manual.</li> <li>The Constant Data Function Block allows for a list of 15 constant data value to be used by the other function blocks. The Axiomatic EA configures the constant data points.</li> <li>The Variable Data Function Block allows for measured process parameters to be stored in a variable memory using user configuration storage event triggers.</li> <li>The Diagnostic Function Block allows the user to implement a PID controller with configurable reference and feedback signals.</li> <li>The PID Control Function Block allows the user to implement a PID controller with configurable reference and feedback signals.</li> <li>The Simplified Lookup Table Function Block is used to give output response up to 3 slopes per input. If more than 3 slopes are needed, then the Programmable Logic Function Block is used to combine up to 2 tables to generate up to 6 slopes. This is a powerful tool. Up to 2 different responses to the same input or three different responses to different inputs can become the input to another function block.</li> </ul>	

	<ul> <li>an associated limit and scaling setpoints. In addition to the simple math blocks, there are also two full featured math blocks with more input signals.</li> <li>The Simplified Timer Function Block allows the user to toggle between two signal sources for a user configurable delay time.</li> <li>The Hysteresis Block implements hysteresis with user configurable transition thresholds.</li> <li>The Set-Reset Block implements Set-Reset logic with user configurable Set and Reset sources.</li> <li>The Simple Conditional Blocks implement conditional logic using up to 4 signal sources.</li> <li>The DTC React Function Block allows for a received DTC from another device on the CAN network to disable an output or act as an input to a function block.</li> <li>The CAN Transmit Function Block sends any output from another function block to the User Manual for details. By default, all messages are sent on Proprietary B PGN's as broadcast messages.</li> <li>The CAN Receive Message Function Block is designed to take any SPN from the CAN network and use it as an input to another function block.</li> <li>The Axiomatic EA will allow for the selection of any ECN Address from 0 to 253 (default is 128). Setpoint configuration files can be saved and used to program additional controllers. (Application-specific control logic is available on request.)</li> </ul>
User Interface	User configuration and diagnostics are provided with the Axiomatic Electronic Assistant KIT, P/Ns: AX070502, AX070505K, or AX070506K. The Axiomatic Service Tool is a <i>Windows</i> -based graphical user interface that allows easy configuration of the controller setpoints.
Approvals	CE marking
Vibration	MIL-STD-202G, Test 204D and 214A (Sine and Random) 10 g peak (Sine), 7.68 Grms peak (Random)
Shock	MIL- STD-202G, Method 213B, test condition A 50g
Diagnostics	Diagnostics messages are provided over the CAN network for the status of inputs or outputs. Each input or output channel could be configured to send diagnostic messages to the network if the I/O goes out of range, In addition to the I/O channels, one other type of fault can be reported to the network using diagnostic messaging, which is an Over Temperature fault (of the controller processor.) The controller stores diagnostic data in a non-volatile log.
Enclosure and Dimensions	High Temperature Nylon housing, (equivalent TE Deutsch P/N: EEC- 5X650B) 4.03 x 4.25 x 1.68 inches 102.44 x 107.96 x 42.67 mm
	L x W x H including integral connector Refer to the dimensional drawing.
Installation	For mounting information, refer to the dimensional drawing. Mounting holes sized for ¼ inch or M6 bolts. The bolt length will be determined by the end-user's mounting plate thickness. The mounting flange of the controller is 0.25 inches (6.35 mm) thick. If the module is mounted without an enclosure, it should be mounted to reduce the likelihood of moisture entry. Install the unit with appropriate space available for servicing and for adequate wire harness access (6 inches or 15 cm) and strain relief (12 inches or 30 cm). Wires should be of the appropriate gauge to meet requirements of applicable electrical codes and suit the specifications of the connector. The module must be mounted in an enclosure in hazardous locations. All field wiring should be suitable for the operating temperature range of the module. All chassis grounding should go to a single ground point designated for the machine and all related equipment.

#### **Dimensional Drawing**



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Form: TDAX020410A-06/15/23